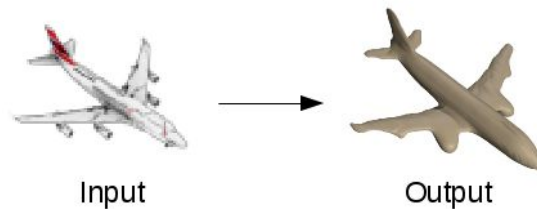


SSR: Semi-supervised Soft Rasterizer for single-view 2D to 3D Reconstruction

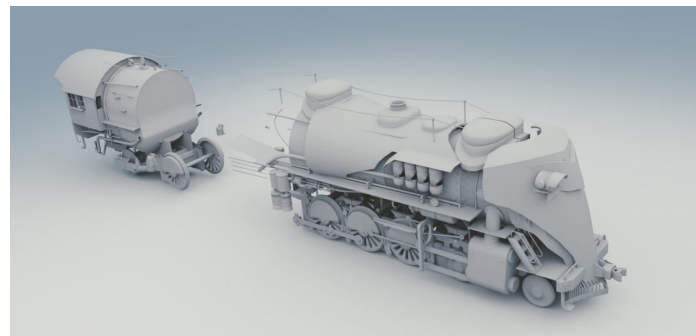
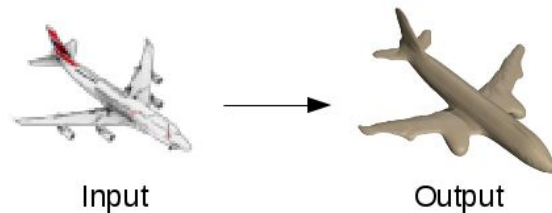
Issam Laradji, Pau Rodriguez, David Vazquez, Derek Nowrouzezahrai

ELEMENT^{AI}



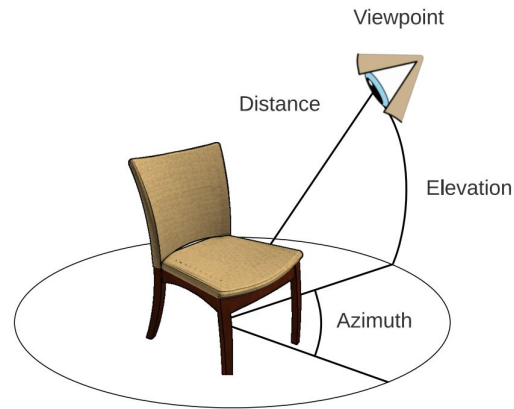
3D reconstruction is impactful

- Applications
 - Autonomous driving, robotics, remote sensing, and medical treatment
- Challenges
 - Manually modelling 3D objects requires a significant amount of human effort.
- **Any attempt at reducing labeling effort is impactful**



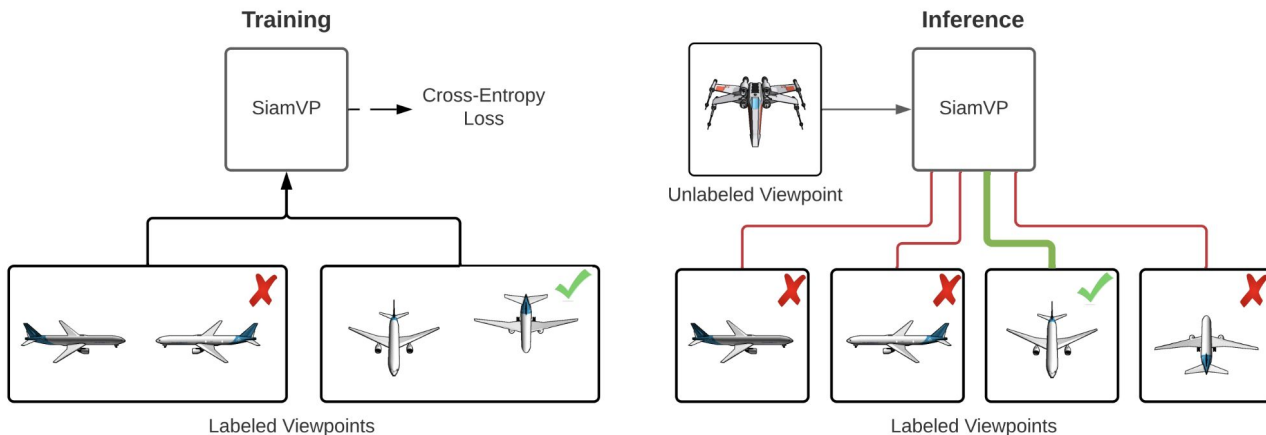
Leverage unlabeled data

- Some differentiable renderers only require viewpoints
 - A viewpoint represents the distance, elevation, and azimuth from a set vantage point
- However,
 - viewpoints might not be readily available
 - And their collection is not trivial
- **Use a semi-supervised learning approach to leverage a large set of unlabeled images**

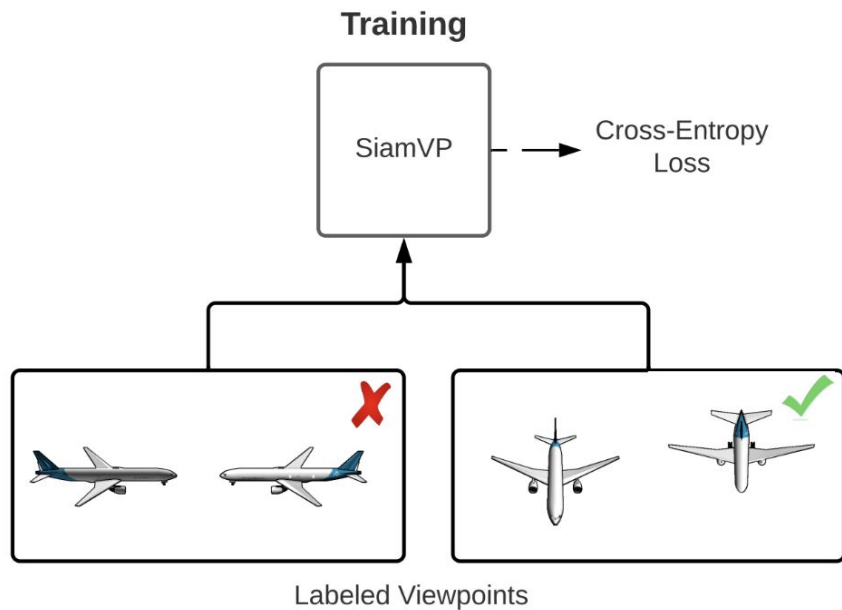


Contributions

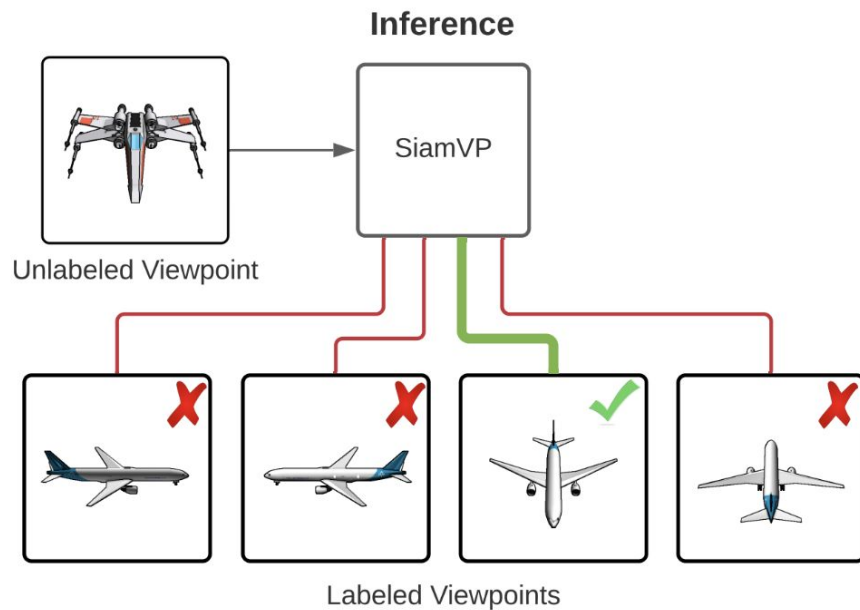
- A novel framework that leverages unlabeled samples for learning to construct 3D meshes
- Extends SoftRas [ICCV'2019] with SiamVP
 - a siamese network that is trained to predict whether two images have the same viewpoint
- Huge boost in performance
 - IoU on ShapeNet for different amounts of labeled data



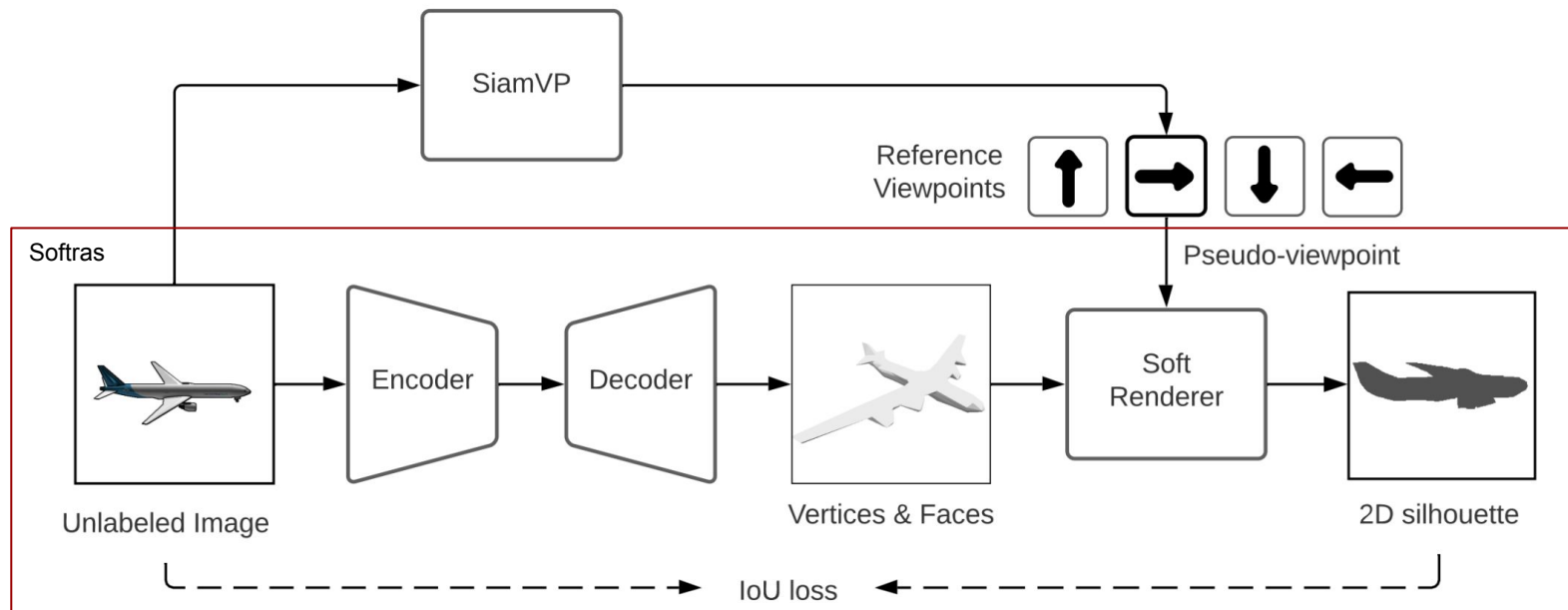
Train on the labeled data



Predict Viewpoints for the unlabeled



Training pipeline



$$\mathcal{L}_s = 1 - \frac{\|\hat{I}_s * I_s\|_1}{\|\hat{I}_s + I_s - \hat{I}_s * I_s\|_1}$$

Experimental Results

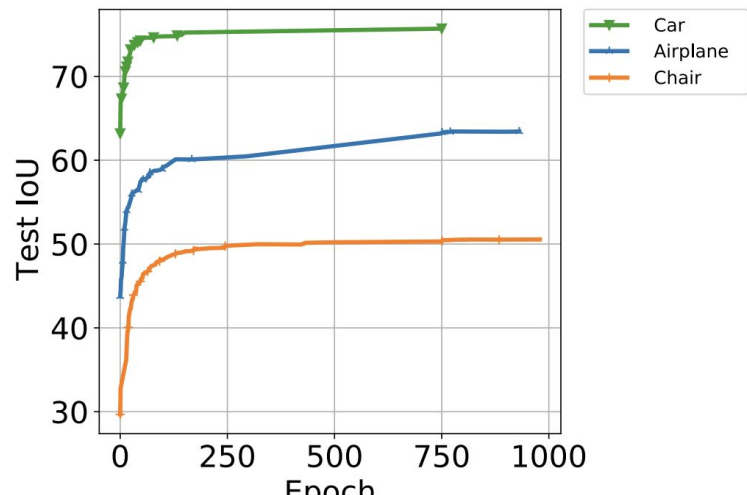
Table 2. IoU results for various objects of ShapeNet, where N is the number of labeled examples.

Method	N	Plane	Bench	Cabinet	Car	Chair	Display	Lamp	Speaker	Rifle	Sofa	Table	Phone	Vessel	Mean
MVC [37]	0	0.38	-	-	0.48	0.35	-	-	-	-	-	-	-	-	-
SoftRas	2	0.42	0.24	0.39	0.6	0.26	0.33	0.17	0.38	0.44	0.38	0.17	0.57	0.28	0.36
SSR (ours)	2	0.55	0.44	0.48	0.75	0.37	0.5	0.27	0.45	0.63	0.53	0.27	0.71	0.53	0.50

Examples from the dataset



Performance as more unlabeled are used



Conclusions

Single-view 2D to 3D Reconstruction

1

A Simple module to leverage unlabeled examples

2

Only few examples need to be labeled with viewpoints

3

Achieved huge boost in performance for 3D reconstruction



GitHub Code:

<https://github.com/IssamLaradji/SSR>